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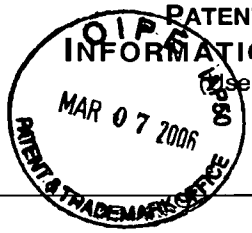

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Ulrich LAGES, et al.	
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U.S. PATENT DOCUMENTS

Ref. Desig.	Examiner's Initials	Document Number	Date	Name	Class/ Subclass	(If appropriate) Filing Date
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FOREIGN PATENT DOCUMENTS

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OTHER DOCUMENTS (including Author, Title, Date, Pertinent Pages, etc.)

Ref. Desig.	Examiner's Initials	
1.	/K.F./	EWALD, A., et al: "LASER SCANNERS FOR OBSTACLE DETECTION IN AUTOMOTIVE APPLICATIONS", Intelligent Vehicles Symposium, 2000. IV 2000. Proceedings of the IEEE Dearborn, MI, USA 3 - 5 Oct., 2000, Piscataway, NJ, USA, IEEE, US, 3 October 2000 (2000-10-03), pages 682 - 687, XP010529017; ISBN: 0-7803-6373-9
2.	/K.F./	Kirchner, A., et al.: "DER LASERSCANNER ALS INTELLIGENTER KFZ-SENSOR" AUTOMATISIERUNGSTECHNISCHE PRAXIS - ATP, OLDENBOURG VERLAG. Munchen, DE, Vol. 40, No. 8. 1998, pages 26 - 32, 34, XP001156940; ISSN: 0178-2320
3.	/K.F./	DIETMAYER, K. C. J., et al.: "MODEL BASED OBJECT CLASSIFICATION AND OBJECT TRACKING IN TRAFFIC SCENES FROM RANGE IMAGES", Proceedings of the Intelligent Vehicles Symposium, XX, XX, 2001, pages 25 - 30, XP009023302
4.	/K.F./	STRELLER, D., et al.: "OBJECT TRACKING IN TRAFFIC SCENES WITH MULTI-HYPOTHESIS APPROACH USING LASER RANGE IMAGES", Proceedings of the World Congress on Intelligent Transport Systems, XX, XX, No. 8, 30 September 2001 (2001-09-30), pages 1 - 8, XP001156926

Examiner:	/Katrina Fujita/	Date Considered:	03/21/2008

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